

This discussion paper is/has been under review for the journal The Cryosphere (TC).
Please refer to the corresponding final paper in TC if available.

Preliminary assessment of model parametric uncertainty in projections of Greenland Ice Sheet behavior

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Received: 19 October 2011 – Accepted: 6 November 2011 – Published: 15 November 2011

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Published by Copernicus Publications on behalf of the European Geosciences Union.

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Abstract

Lack of knowledge about the values of ice sheet model input parameters introduces substantial uncertainty into projections of Greenland Ice Sheet contributions to future sea level rise. Computer models of ice sheet behavior provide one of several means of estimating future sea level rise due to mass loss from ice sheets. Such models have many input parameters whose values are not well known. Recent studies have investigated the effects of these parameters on model output, but the range of potential future sea level increases due to model parametric uncertainty has not been characterized. Here, we demonstrate that this range is large, using a 100-member perturbed-physics ensemble with the SICOPOLIS ice sheet model. Each model run is spun up over 125 000 yr using geological forcings, and subsequently driven into the future using an asymptotically increasing air temperature anomaly curve. All modeled ice sheets lose mass after 2005 AD. After culling the ensemble to include only members that give reasonable ice volumes in 2005 AD, the range of projected sea level rise values in 2100 AD is 30 % or more of the median. Data on past ice sheet behavior can help reduce this uncertainty, but none of our ensemble members produces a reasonable ice volume change during the mid-Holocene, relative to the present. This problem suggests that the model's exponential relation between temperature and precipitation does not hold during the Holocene, or that the central-Greenland temperature forcing curve used to drive the model is not representative of conditions around the ice margin at this time (among other possibilities). Our simulations also lack certain observed physical processes that may tend to enhance the real ice sheet's response. Regardless, this work has implications for other studies that use ice sheet models to project or hindcast the behavior of the Greenland ice sheet.

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The Greenland Ice Sheet is projected to contribute to sea level change by 2100 AD (Meehl et al., 2007) and beyond, but both the rate of ice mass loss and its eventual magnitude are unknown. The ice sheet contains enough ice to raise mean sea level worldwide by about 7.2 m (Bamber et al., 2001), if totally melted. Satellite measurements suggest that the ice sheet's mass balance is negative and perhaps becoming more so with time (Velicogna, 2009; Alley et al., 2010, and references therein; Zwally et al., 2011). Scaling arguments suggest ~0.1–0.5 m of mean sea level rise due to Greenland ice loss by 2100 AD (Pfeffer et al., 2008). Pfeffer et al. (2008) argue that the lower end of this range is more plausible than the higher end, because the larger number requires a rapid factor-of-10 increase in ice velocities. However, the difference between the ends of this range is economically important (e.g., Sugiyama et al., 2008), indicating a need for further investigation.

Ice sheet models provide an additional way of assessing future sea level change due to Greenland ice loss (e.g., Huybrechts and de Wolde, 1999; Greve, 2000; Gregory and Huybrechts, 2006; Price et al., 2011). These models typically include simplified treatments of ice flow, basal sliding, snowfall, and surface melting. The ice sheet modeling community has developed advanced treatments of all these processes, plus enhanced basal flow due to surface melting, ice shelf growth, calving, and sub-shelf melt (e.g., Parizek and Alley, 2004; Alley et al., 2008; Pollard and DeConto, 2009; Walker et al., 2009; Bueler and Brown, 2009; Robinson et al., 2010; Price et al., 2011). These new treatments are not implemented in all models at the present time. However, the models show remarkable success in simulating many aspects of ice sheet behavior over millennial time scales and longer (e.g., van Tatenhove et al., 1995, 1996; Greve, 1997; Simpson et al., 2009; Pollard and DeConto, 2009).

Remaining challenges in assessing future Greenland Ice Sheet changes include (1) characterizing model response to parameter choices, (2) establishing an initial state for prognostic simulations, and (3) matching data on the ice sheet's past behavior (van

der Veen, 2002; Heimbach et al., 2008; Aschwanden et al., 2009; Stone et al., 2010; Greve et al., 2011). Ice sheet models have many uncertain parameters, and the choice of parameter values has a strong influence on modeled behavior (Stone et al., 2010; Greve et al., 2011). Because the thermal field within the ice sheet is mostly unknown (cf. Greve, 2005), ice sheet models are “spun up” to the present using reconstructed former surface temperatures and sea levels. Achieving a good match between the modeled and observed ice thickness distributions at the end of this spinup is challenging (Aschwanden et al., 2009; Greve et al., 2011). In general, simulated ice volumes at the ends of spin-up runs are larger than expected (e.g., Heimbach et al., 2008; Stone et al., 2010; Robinson et al., 2010; Vizcaino et al., 2010; Greve et al., 2011; cf. Bamber et al., 2001). Finally, data on past ice sheet variations (e.g., Alley et al., 2010, and references therein) provide a check on ice sheet models: if a model reproduces past changes well, then we can have more confidence in its projections of future changes (cf. Oreskes et al., 1994).

Perturbed physics tuning exercises may help address these challenges. In a perturbed physics ensemble, the model is run many times with different parameter combinations to identify a group of runs that provide a reasonable fit to observations, usually the modern geometry of the ice sheet (e.g., Ritz et al., 1997; Stone et al., 2010; Greve et al., 2011; for fits to paleo-data, see Tarasov and Peltier, 2003; Lhomme et al., 2005; Simpson et al., 2009). These “good” ensemble members are likely more reliable estimators of future behavior than the ensemble as a whole (cf. Weigel et al., 2010). This approach is well established in climate modeling (e.g., climateprediction.net; Stainforth et al., 2005; Piani et al., 2005), and a small but growing number of ice sheet modeling studies use ensemble methods (e.g., Tarasov and Peltier, 2004; Napieralski et al., 2007; Hebel et al., 2008; Stone et al., 2010).

In this paper, we present results from a small perturbed-physics ensemble with the ice sheet model SICOPOLIS (Greve, 1997; Greve et al., 2011; sicopolis.greveweb.net). Our approach builds on existing work by Stone et al. (2010) by using a spinup procedure that takes past climate variability into account and is agreed upon by the ice sheet

modeling community (seaRISE partners, 2008; Greve et al., 2011). The results indicate that our present uncertainty about the best values of model parameters translates to a large spread among model-based projections of future Greenland Ice Sheet behavior.

85 The paper proceeds as follows. We describe the ice sheet model, ensemble design, climate forcing time series, and ensemble culling in Sect. 2, Methods. Section 3, Results, describes similarities and differences among the ensemble members during different parts of the model spinup period, then discusses the effects of ensemble culling on the range of model-projected future sea level increases from the Greenland ice sheet. 90 Section 4, Discussion, treats the success of our ensemble in addressing the three challenges in ice sheet modeling identified above. Section 5, Conclusions, emphasizes the main outcomes of the study and provides some caveats that should be borne in mind when interpreting our model output.

2 Methods

95 Briefly, we applied the Latin hypercube ensemble methods of Stone et al. (2010) to the SICOPOLIS ice sheet model, as set up by Greve et al. (2011). The Latin hypercube method provides a quasi-random sampling of parameter space that is more even than that produced by Monte Carlo methods (Bevington and Robinson, 2003; Saltelli et al., 2008) and avoids wasting model evaluations on uninformative parameters, as can 100 happen with a grid design (Urban and Fricker, 2009). We can thus make a reasonable exploration of parameter space with a relatively small number of model evaluations.

2.1 Model description

As noted above, we carried out our simulations with the SICOPOLIS ice sheet model. SICOPOLIS has been previously described by Greve (1997) and Greve et al. (2011), 105 and we refer interested readers to those papers for more information. The model is broadly comparable to most other large-scale ice sheet models, such as Glimmer (Rutt et al., 2009).

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The model setup that we use is specifically intended for the problem of projecting future sea level change (Greve et al., 2011). It includes a horizontal resolution of 110 10 km, with 81 grid points in the vertical direction. These points are concentrated near the base, where the bulk of ice deformation occurs. The model time step is 1 yr.

Use of the SICOPOLIS model allows us to incorporate many thousands of years of geological data into model spinup (Sect. 2.3, below). As with most Greenland ice sheet models, SICOPOLIS calculates stresses within the ice body using the shallow-ice approximation (e.g., Hutter, 1983; Greve and Blatter, 2009). This approximation is 115 reasonable over the bulk of the ice sheet (perhaps 70–80 % by area, and a greater percentage by volume), but fails in areas where the real ice sheet exhibits fast flow, such as in ice streams (see Joughin et al., 2010, for surface velocity maps). Higher-order models provide improved representations of ice flow where the shallow-ice approximation 120 fails (Pattyn et al., 2008; Hindmarsh, 2009), but typically require more computing time than shallow-ice models. To our knowledge, higher-order models have not yet been used to carry out long integrations like those we undertake here with SICOPOLIS.

2.2 Ensemble design

We vary five model parameters among 100 ensemble members (Fig. 1; Supplementary 125 Material). The number of model runs was chosen to achieve a reasonable tradeoff between covering parameter space and minimizing computation time. For comparison, our total number of evaluated model time steps (12.65×10^6) is slightly larger than that of Stone et al. (2010), who performed a larger number of shorter model runs.

The free parameters (and their ranges) include the ice flow enhancement factor 130 (1–5, dimensionless), ice and snow positive degree-day factors (“PDD factors”; 5–20 mm day⁻¹ °C and 1–5 mm day⁻¹ °C, respectively); the geothermal heat flux (30–70 mW m⁻²), and the basal sliding factor (0–20 m yr⁻¹/Pa). The ice flow enhancement factor corrects for differences between the rheology of ice as it is measured in the laboratory and that observed on an ice sheet scale; these differences are likely due to 135 impurities and anisotropic fabric within the ice (Greve, 1997, his Eqs. 3 and 4; see also

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Rutt et al., 2009, their Eq. 9). The positive degree-day factors describe a statistical relationship between surface temperatures and the rate of surface lowering (Braithwaite, 1995; Calov and Greve, 2005). The geothermal heat flux varies over the Earth's surface, but is difficult to measure under the ice sheet (see discussion in Stone et al., 2010); thus, it is often taken to be constant for purposes of ice sheet modeling (e.g., Ritz, 1997). Finally, the basal sliding factor determines how rapidly the ice slides over its bed where the interface is not frozen (Greve and Otsu, 2007, their Eq. 2).

For the first four parameters, the ranges are roughly the same as those investigated by Stone et al. (2010), who based their ranges on data-based studies from the literature (e.g., Dahl-Jensen and Gundestrup, 1987; Braithwaite, 1995). We expanded the ranges for the positive degree-day factors so that the EISMINT-3 preferred values (Huybrechts et al., 1998) lie well within the investigated range, instead of at one end, as in Stone et al. (2010). We also expanded the range of the geothermal heat flux parameter; Stone et al. (2010) found that this parameter was relatively unimportant, and we hypothesized that a larger range might show an effect. The range we investigate is still within previous estimates (Greve, 2005; Bucharadt and Dahl-Jensen, 2007; Stone, 2010). The basal sliding parameter ranges from 0 to about double the best value identified by Greve and Otsu (2007).

This list of free parameters is somewhat different from that used by Stone et al. (2010), but consistent with Ritz et al. (1997), in that we fix the atmospheric temperature lapse rates (Fausto et al., 2009) and include the basal sliding factor as a free parameter. In effect, we take the surface temperature and precipitation as given, even though these data sets contribute additional uncertainty to projected ice volumes (van der Veen, 2002; Stone et al., 2010).

2.3 Initial condition and climate forcing time series

All runs were driven by the same surface temperature, precipitation, and sea level forcings. The paleoclimate spinup (Fig. 2) closely resembles that of Greve et al. (2011). We began with the observed modern ice thickness and bedrock elevation grid (Bamber

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et al., 2001) at -125 ka, during the Eemian interglacial. This initial condition is not ideal; much work shows that the ice sheet contained ~ 30 – 85 % of its present volume during the Eemian (Alley et al., 2010, and references therein). However, the errors in the initial condition should average out over the spinup period (see discussion in Rogozhina et al., 2011).

From 125 ka onward, we drove the model using a temperature anomaly curve based on the GRIP oxygen isotope record (Dansgaard et al., 1993; Johnsen et al., 1997) and background sea levels from the SPECMAP compilation of oxygen isotope measurements in deep-sea sediment cores (Imbrie et al., 1984). Precipitation changes by ~ 7 % for each degree of temperature change relative to the present (Greve et al., 2011, their Eq. 6; cf. van der Veen, 2002). The transfer functions for converting oxygen isotope measurements to surface temperatures and sea levels are given in Greve et al. (2011). Modern-day surface temperatures and precipitation values are from Fausto et al. (2009) and Ettema et al. (2009); these patterns are scaled in the model according to the calculated temperature and precipitation anomalies.

Near the end of the paleoclimate spinup, we substituted an instrumental record of southwestern Greenland mean annual temperature anomalies (Vinther et al., 2006) for the GRIP-based temperatures (Fig. 2). The Vinther et al. (2006) compilation covers the years 1784–2005 AD; we chose to begin the instrumental period in 1840, when the number of missing temperature records per year becomes noticeably smaller. Use of the Vinther et al. (2006) temperatures helps us to capture the interannual variability that could be important in explaining modern mass balance trends (Alley et al., 2010; Zwally et al., 2011).

After 2005, the surface temperature anomaly increases according to

$$T_f(t) = \Delta T \times [1 - \exp(-\Delta t/\tau)]. \quad (1)$$

In this expression, ΔT is the final temperature anomaly (6°C) above mean annual 1840–1869 AD temperatures, less the mean 1976–2005 AD temperature anomaly ($\sim 1^\circ\text{C}$); Δt is the year less 2005 AD; and τ is the time scale (100 yr). The form of

up ice sheet models also contribute to projection uncertainty (Stone et al., 2010; see also Rogozhina et al., 2011). Finally, future ice volumes depend on uncertain emissions trajectories and the broader climate system's response (Meehl et al., 2007).

Even our most responsive model runs may underestimate mass loss from the real ice sheet. If precipitation remains constant in the future, instead of increasing at $\sim 7\%$ /degree C of warming (Sect. 2.3; Greve, 2011), then the ice sheet will shrink more rapidly than we project. There are a number of mechanisms for rapid ice loss that are not included in this ensemble. For example, surface melting may lead to basal lubrication and enhanced transport of ice to the margin (Zwally et al., 2002; Parizek and Alley, 2004; Bartholomew et al., 2010). We neglect this possibility here; see Greve and Otsu (2007) for model runs with SICOPOLIS that include this effect. Additionally, ocean warming may contribute to mass loss where the ice is in contact with the water (Straneo et al., 2010), and the resulting rapid thinning of marine ice margins could then propagate up ice streams to the central parts of the ice sheet. This scenario cannot be captured by shallow-ice models like SICOPOLIS, but is expected to appear in higher-order models. Complex models typically have more parameters than simpler ones, so sensitivity experiments with higher-order models (e.g., Price et al., 2011) might lead to a wider range of future Greenland states (cf. Saltelli et al., 2008).

Given these problems, both our uncertainty estimates and our projections of future ice sheet mass loss may be too small. Despite the large variation among individual model runs, all of our modeled ice sheets lose mass from 2005 AD onwards. Thus, our work agrees with the scientific consensus, which says that sea level rise due to enhanced mass loss from the Greenland ice sheet in the face of surface temperature increases is very likely (Lemke et al., 2007).

Supplementary material related to this article is available online at:
<http://www.the-cryosphere-discuss.net/5/3175/2011/tcd-5-3175-2011-supplement.zip>.

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Acknowledgements. We thank the seaRISE project members for compiling the input data sets and making them available on the Web (<http://websrv.cs.umt.edu/isis/index.php/Data>). R. Alley, J. Seguinot, Y. Axford, and D. Pollard provided helpful discussions and comments on the manuscript. P. Applegate thanks the Wednesday morning discussion group at Stockholm University for much useful feedback. Support for P. Applegate was provided by the Bert Bolin Climate Centre at Stockholm University through a postdoctoral fellowship. R. Greve was supported by a Grant-in-Aid for Scientific Research A (No. 22244058) from the Japan Society for the Promotion of Science. Partial support from the US Department of Energy and the Penn State Center for Climate Risk Management is gratefully acknowledged. The data processing for this paper was done in Octave (<http://www.octave.org>), and the figures were made with Octave and Inkscape (<http://www.inkscape.org>). This paper is a contribution from the Bert Bolin Centre for Climate Research, Stockholm University.

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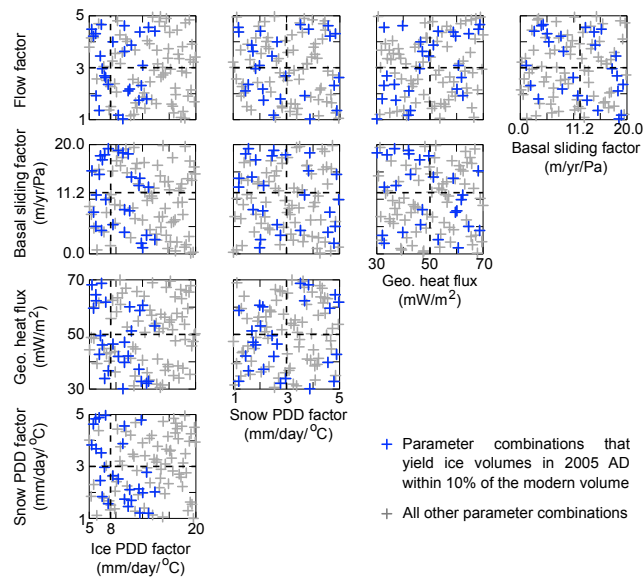


Fig. 1. Parameter combinations used in the perturbed-physics ensemble, as projected onto two-dimensional slices through the five-dimensional space. Dashed lines indicate EISMINT-3 best estimates for most model parameters (Huybrechts, 1998; Stone et al., 2010), except the basal sliding factor, which comes from Greve and Otsu (2007). Blue crosses indicate parameter combinations that are consistent with the modern ice volume after model spinup (within 10% of the estimated modern ice volume in 2005 AD; Sect. 2.2).

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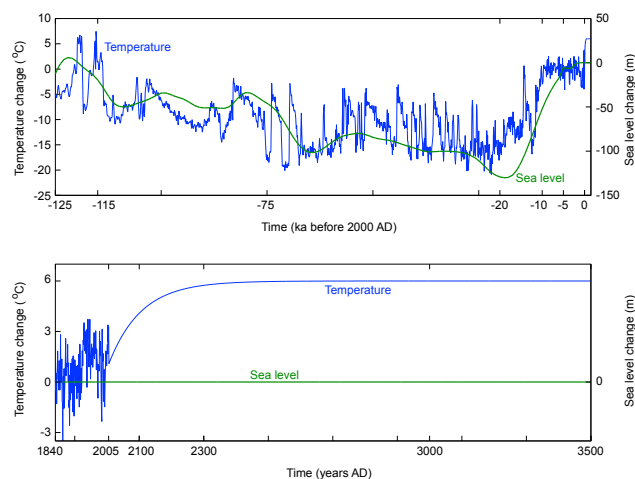


Fig. 2. Surface temperature (blue) and background sea level (green) curves used to drive the ice sheet model simulations. Top panel, full extent of runs (–125 ka to 3500 AD; 2000 AD is indicated by 0); bottom panel, 1840 AD to 3500 AD. Temperature and sea level curves for –125 ka through 1840 AD come from the seaRISE project (http://websrv.cs.umt.edu/isis/index.php/SeaRISE_Assessment; seaRISE partners, 2008; Greve et al., 2011), and are based on oxygen isotopes in ocean sediment cores (Imbrie et al., 1984) and in central-Greenland ice cores (Dansgaard et al., 1993; Johnsen et al., 1997). 1840–2005 AD temperatures come from southwestern Greenland observations (Vinther et al., 2006). Future temperatures assume an asymptotic increase to ~5 degrees C above 1976–2005 levels, with a time scale of 100 yr (Greve, 2000; see text). Background sea level is held constant from 1840–3500 AD. Labeled tick marks are those referred to in the text and figures; unlabeled tick marks are 25 ka apart in the top panel and 200 yr apart in the lower panel.

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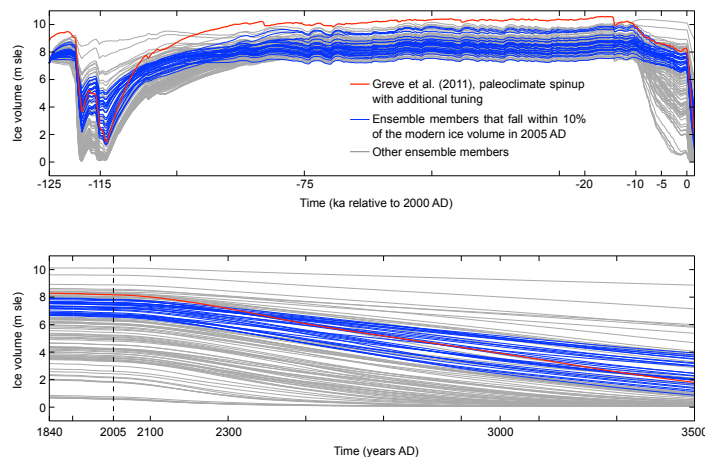


Fig. 3. Simulated ice volumes as a function of time for all 100 ensemble members, expressed in meters of sea level equivalent (m sle). All model runs begin at -125 ka before 2000 AD from the observed modern ice geometry, with an ice volume of ~ 7.2 m sea level equivalent (Bamber et al., 2001; see text). Blue curves, model runs that give ice volumes within 10% of estimated modern ice volume in 2005 AD (dashed line). Red line, time evolution of the “paleoclimate spinup with additional tuning” model run described by Greve et al. (2011). Labeled tick marks are those referred to in the text and figures; unlabeled tick marks are 25 ka apart in the top panel and 200 yr apart in the lower panel.

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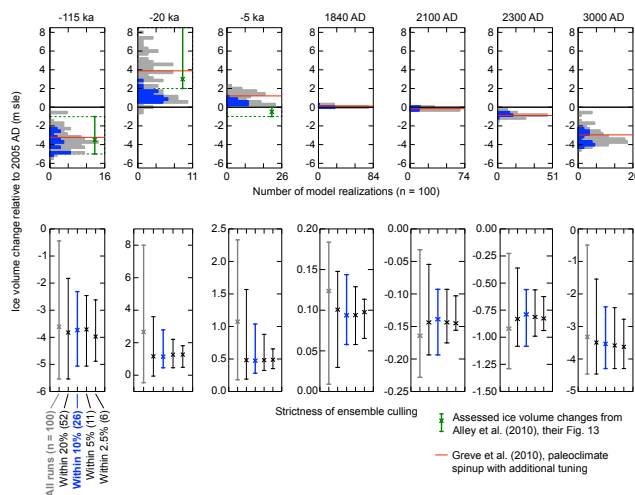


Fig. 4. Histograms of modeled ice volume change relative to 2005 AD (top) and the effects of different assumed uncertainties for the modern ice volume on the median and range of ice volume change projections and hindcasts (bottom). Y-axis scaling is the same for all panels in the top row, but differs among panels in the bottom row. Color coding is the same as in Fig. 2; gray, all model runs; dark blue, model runs that lie within 10% of the estimated modern ice volume in 2005 AD; red line, “paleoclimate spinup with additional tuning” model run from Greve et al. (2011). The green points with error bars in the top panels indicate assessed changes in the ice sheet, relative to the modern, from Alley et al. (2010, their Fig. 13). None of our model runs produce a smaller-than-today ice volume during the mid-Holocene (-5 ka). For the future time slices (2100, 2300, and 3000 AD), the range of potential future ice volume changes is always at least 30% of the median, regardless of how strictly the ensemble is culled.

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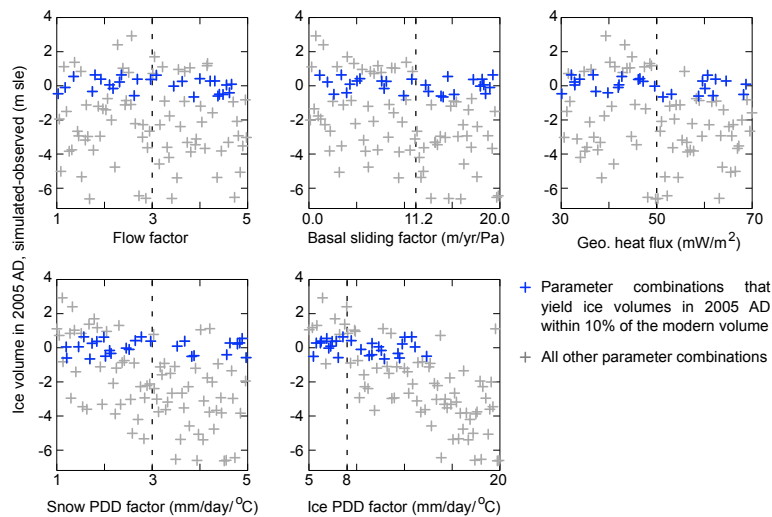


Fig. 5. Relation between input parameter values and simulated ice volumes in 2005 AD, for all ensemble members (gray crosses) and runs that lie within 10% of the estimated modern ice volume (blue crosses). Vertical dashed lines indicate EISMINT-3 best estimates for most model parameters (Huybrechts, 1998; Stone et al., 2010), except the basal sliding factor, which comes from Greve and Otsu (2007). Influential parameters are indicated by points that are tightly arranged about a curve that dips steeply from one side of the plot to the other (Saltelli et al., 2008). In our ensemble, the ice positive degree-day factor has the greatest influence on simulated modern ice volume, with the snow PDD factor and the basal sliding factor taking second and third places. However, ice PDD factors greater than $\sim 15 \text{ mm day}^{-1} \text{ } ^\circ\text{C}$ appear inconsistent with the modern ice volume constraint.

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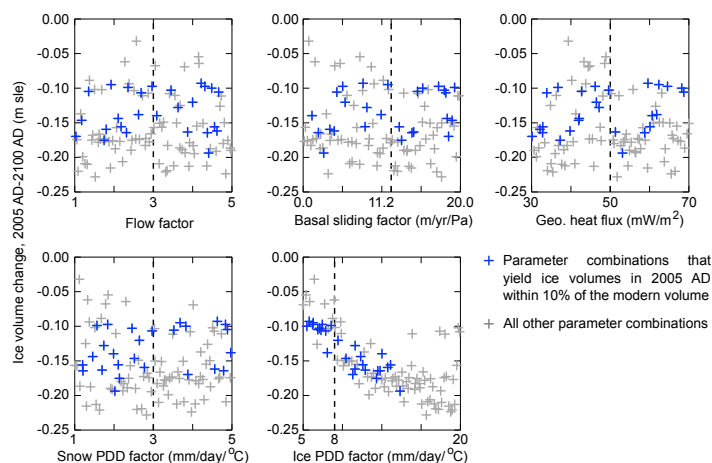


Fig. 6. Relation between input parameter values and simulated ice volume changes between 2005 and 2100 AD (Fig. 3). Color coding is the same as in Fig. 5. The ice positive degree-day factor appears to dominate the short-term future behavior of the model.

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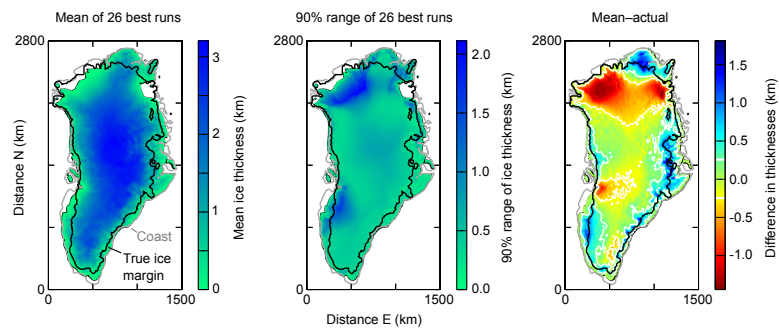


Fig. 7. Comparison of the spatial distribution of mean ice thickness among the 26 “best” model runs to the observed modern ice geometry. By “best” runs, we mean those that give ice volumes within 10 % of the estimated modern ice volume in 2005 AD (Bamber et al., 2001; Sect. 2.2, 3.5). 90 % range, difference between 95th and 5th percentiles of ice thickness values within each grid cell. Black line, modern ice margin; gray line, coast (Bamber et al., 2001, as gridded by Greve et al., 2011); white line, contour bounding areas where the differences between the observed and mean modeled ice thicknesses are less than 250 m. Simulated ice volumes are generally too large near the margins, but there are large areas of too-thin ice in the northern part of Greenland and upflow from Jakobshavn (about a third of the way northward on the western side).