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## Changes in Imja Tsho in the Mt. Everest region of Nepal

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# Changes in Imja Tsho in the Mt. Everest region of Nepal

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## Abstract

Imja Tsho, located in the Sagarmatha (Everest) National Park of Nepal, is one of the most studied and rapidly growing lakes in the Himalayan range. Compared with previous studies, the results of our sonar bathymetric survey conducted in September 2012 suggest that the maximum depth has increased from 98 m to  $116 \pm 0.25$  m since 2002, and that its estimated volume has grown from  $35.8 \pm 0.7$  million  $\text{m}^3$  to  $61.6 \pm 1.8$  million  $\text{m}^3$ . Most of the expansion of the lake in recent years has taken place in the glacier terminus–lake interface on the eastern end of the lake, with the glacier receding at about  $52.6 \pm 0.3 \text{ myr}^{-1}$  and the lake expanding in area by  $0.039 \pm 0.0195 \text{ km}^2 \text{ yr}^{-1}$ . A ground penetrating radar survey of the Imja-Lhotse Shar glacier just behind the glacier terminus shows that the ice is over  $217 \pm 12.71$  m thick in the center of the glacier. The volume of water that could be released from the lake in the event of a breach in the damming moraine on the western end of the lake has increased from 21 million  $\text{m}^3$  in 2002 to  $34.8 \pm 0.54$  million  $\text{m}^3$  in 2012.

## 1 Introduction

The formation of glacial lakes in the Nepal Himalaya has been increasing since the early 1960s (Gardelle et al., 2011). Twenty-four new glacial lakes have formed, and 34 have grown substantially in the Sagarmatha (Mt. Everest) and Makalu-Barun National Parks of Nepal during the past several decades (Bajracharya et al., 2007). Accompanying this increase in the number and size of glacial lakes is an associated increase in the risk of glacial lake outburst flood (GLOF) events (Ives et al., 2010; Shrestha and Aryal, 2011). At least twelve of the new or growing lakes within the Dudh Koshi watershed of this region may be of concern based on their rapid growth as evidenced by comparative time lapse, remotely sensed imagery over the past several decades (Bajracharya et al., 2007; Jianchu et al., 2007; Bolch et al., 2008; Watanabe et al., 2009).

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at 80 uniformly spaced points on the lake, both using a weighted line technique. We conducted a bathymetric survey of Imja Tsho during 22–24 September 2012 using a Biosonic Habitat EchoSounder MX sonar unit mounted on an inflatable raft. The sonar unit has an accuracy of  $2.7\text{ cm} \pm 0.2\%$  of depth and a maximum depth of operation of 100 m with the available transducer. Several transects were made around the lake with the sonar unit measuring the depth (Fig. 2).

For areas with depths greater than 100 m where the equipment could not measure depth it did record the position of those points. To estimate the depth of the lake in these areas, interpolation was made with values of the shallower, measured points by establishing transects crossing the lake from north to south over these deep areas. The lake bottom shape along these transects is assumed to be parabolic fit and an interpolation is fit to the measured points and used to estimate the depths at the missing points.

During the survey, large icebergs blocked access to the eastern end of the lake, so interpolation was used to fill in missing values in this area. Robertson et al. (2012) found that ice ramps at the glacier end of glacial lakes tend to have slopes  $11\text{--}30^\circ$  and exhibit subaqueous calving. To fill in the missing values, we assume that the lake bottom in the eastern part of the lake is comprised of an ice ramp sloping up toward the glacier terminus and that the ice ramp has a slope of  $10\text{--}30^\circ$  in the first 150 m near the glacier;  $10\text{--}20^\circ$  in the next 150 m, and  $2\text{--}5^\circ$  until the measured points are reached. Three transects, north to south, at 150, 300 and 450 m from the eastern shoreline with the shape of the eastern-most measured transect are used for interpolation. The lake depth at the points along the three lines were calculated so that they agree with the slopes described by Robertson et al. (2012). Since these slopes have maximum and a minimum values, each point along these lines also has a maximum and a minimum value as well that can be used in the uncertainty calculations described below.

In calculating the uncertainty associated with the lake volume, we consider the uncertainty in the depth measurements, and the uncertainty in the slope of the ice ramp, but not the uncertainty in the lake area. The uncertainty of the lake volume calcula-

tions are estimated using a range of depth for each point that was interpolated in areas deeper than 100 m or estimated from ice ramp slopes on the eastern end of the lake. In the areas where the depth of the lake was measured with the sonar device, we could directly calculate the maximum and minimum values using the error of the equipment.

For points in areas deeper than 100 m that were interpolated, maximum and minimum depth values were calculated on 5 m raster files, thus providing two values for each 25 m<sup>2</sup>. Using the points that were either measured, interpolated in areas deeper than 100 m or estimated using ice ramp slopes, two 5 m resolution raster files were generated, one for the maximum depth and one for the minimum depth. Thus, each point has two values representing the maximum and minimum depth for each cell of 25 m<sup>2</sup>. We assume that the depth in each cell follows a uniform probability distribution (US-ACE, 2003), so that any depth within the maximum to minimum depth range has an equal probability of being the actual depth of the cell. In order to calculate the volume of the lake we used a Monte Carlo simulation with 2000 samples, which allows us to include the uncertainty in our measurement and assumptions; and calculate the expected value and standard deviation of the water volume.

## 2.2 Lake area calculation

Bathymetric surveys of Imja Tsho conducted in April 1992 (Yamada and Sharma, 1993), April 2002 (Sakai et al., 2003), and September 2012 (this study) are compared here. Landsat satellite imagery is used to compare the areal expansion of Imja Tsho with the changes in bathymetry. Unfortunately, Landsat images from the exact dates of the bathymetric surveys are not available, so the images selected are as close to the survey dates as possible. The images comprise a Landsat-4 image from 4 July 1992 and Landsat-7 images from 4 October 2002 and 29 September 2012. The processing level of the Landsat images are all L1T, indicating that the images are all geometrically rectified using ground control points from the 2005 Global Land Survey in conjunction with the 90 m Shuttle Radar Topographic Mission (SRTM) global DEM. The swipe visualization tool in PCI Geomatica 2013 was used with Landsat band 7 from each image

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to confirm that the images were properly co-registered. The co-registered images were used to compute changes in the areal extent of Imja Tsho.

The normalized differential water index (NDWI) was used to semi-automatically compute the area of the lake. Previous studies have computed the NDWI using NIR and Blue bands (Huggel et al., 2002; Bolch et al., 2008) or the NIR and Green bands (McFeeters, 1996). Frey et al. (2010) used a combination of the NDWI computed with the NIR and Blue band along with the ratio of the NIR and SWIR bands to delineate glacial lakes in the Swiss Alps. This study tested computing the NDWI with several different band combinations (e.g., Blue, NIR, SWIR) with the aim of identifying a single band combination and a threshold value that could be applied to the three Landsat images to precisely delineate Imja Tsho. The NDWI using the NIR (Band 4) and SWIR (Band 5) bands of the Landsat satellites with a threshold of zero was found to yield the best results. These bands are typically used to delineate glaciers, but were found to be the most effective in this study particularly when dealing with delineating the boundary of the lake even when large debris-covered icebergs were present near the calving front. It is possible that Imja Tsho being located on a debris-covered glacier may have aided the effectiveness of this particular band combination. Nonetheless, large debris-covered icebergs near the glacier calving front may still cause pixels to be misclassified as land rather than water. These pixels are manually corrected in post-processing. Furthermore, at the calving front it can be difficult to distinguish the lake and icebergs from melt ponds located immediately behind the calving front. To prevent misclassification of the calving front, pixels classified as water that are not cardinally connected to the lake are classified as melt ponds. The perimeter of the lake, which is used to quantify uncertainty, is defined as any water pixel that has a land pixel in any cardinal or diagonal direction. The maximum error associated with the NDWI estimated lake areas is the number of perimeter pixels multiplied by half the area of a pixel, since pixels on the perimeter that are more than half land would be classified as land.

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## 2.3 Calving retreat of Imja-Lhotse Shar Glacier

The calving front was defined in the NDWI image processing as the last pixel in each row that has a lake pixel to its left and a land pixel to its right. A problem arises in the southern-most calving front pixels in which a calving front pixel is defined in a later image, but is not defined in an earlier image because the lake's width expanded. In this circumstance (which occurs three times between the 1992 and 2002 images and two times between the 2002 and 2012 images) the calving front pixel for the older image is considered equal to the closest calving front pixel. The calving rate for a row may then be computed as the difference between calving front pixels within a given row. The maximum error in this calving rate estimate is one pixel.

## 2.4 Ground penetrating radar survey

In order to better understand the structure of the Imja-Lhotse Shar glacier in the proximity of the eastern end of Imja Tsho, a Ground Penetrating Radar (GPR) survey was conducted there. The transect of the survey is shown in Fig. 2. The equipment for the GPR survey was a custom built, low frequency, short-pulse, ground-based radar system. Gades et al. (2000) used a similar system on the debris-covered Khumbu glacier near Imja Tsho, but it was not configured for moving transects. The GPR transmitter was a Kentech Instruments Ltd. GPR pulser outputting 4 kV signals with a 12 V power source. The receiving antenna is connected to an amplifier and a National Instruments USB-5133 digitizer whose output feeds into a LabView program for immediate processing in the field and correlation with GPS signals. Using a common offset, in-line deployment, the GPR pulses are transmitted and received through 10 MHz weighted dipole antennae threaded inside climbing webbing. Post-processing steps performed on the data included: removal of pre-trigger points; deglitching; demeaning with smoothing of the mean trace; detrending; bandpass filtering; conversion of two-way travel time to depth when radar velocity is available; depth stripping; and normalizing by maximum absolute value.

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2.58±0.25 million m<sup>3</sup> yr<sup>-1</sup>. Compared to the prior surveys, the results of this study show that the eastern region of the lake has deepened over the last decade (2002–2012) as the ice beneath has melted, with the average depth increasing by 0.64±0.3 m yr<sup>-1</sup> and the maximum depth by 2.58±0.08 m yr<sup>-1</sup>. Figure 4 shows the 2012 bathymetric survey results along section A-A' from Fig. 3 along with those of the 1992 and 2002 surveys (Sakai et al., 2003, Fig. 4, p. 559), indicating an eastward expansion of the lake, rapid retreat of the glacier ice cliff and the subaqueous melting that has taken place.

Two distinct zones of Imja Tsho with different depths are illustrated in Fig. 4: zone A, from 0 m to 1000 m on (western part), and zone B, from 1000 m to 2100 m (eastern part). The exact separation between these two zones is unknown, but it is estimated from the bathymetric data to occur at about 1000 m in Fig. 4. Reasons for the differences in depth between the two zones are not entirely clear, but may be related to the presence or lack thereof of ice at the lake bottom. That is, a lack of ice at the bottom of zone A would arrest all further deepening, while the presence of ice at the bottom of zone B would account for its continued deepening. This might also be due to the presence of a thick debris cover on the ice at the bottom of zone A but not in zone B. When the lake grew to form the western part (zone A), the growth rate was smaller; therefore, more debris might have deposited on the lake bottom.

### 3.2 Areal expansion of Imja Tsho

The NDWI classifications of water pixels for the Landsat images described previously are shown in white in Fig. 5 for 2012. All the images have pixels identified as melt ponds and the 2012 image has debris-covered icebergs in the lake area, both of which are manually corrected for in post-processing. The lake areas derived from the 1992, 2002, and 2012 images are shown in Table 2. The estimated 1992 lake area of 0.648±0.073 km<sup>2</sup> agrees very well with the 0.60 km<sup>2</sup> lake area estimated by Yamada and Sharma (1993) in April 1992. The difference between these two measurements may be due to the lake expansion during the 1992 melt season and/or the error associated

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with the satellite image. The NDWI estimated 2002 lake area of  $0.867 \pm 0.091 \text{ km}^2$  also agrees well with the  $0.86 \text{ km}^2$  area that Sakai et al. (2003) estimated, although the satellite imagery methods used in the referenced study were not described. The good agreement between the NDWI estimated areas and the previous studies demonstrates the effectiveness of using NDWI to outline the lake. The maximum errors for the three images are shown in Table 2. The areal expansion of Imja Tsho over the last 50 years is shown in Fig. 6. The decadal expansion rate has increased to  $0.039 \pm 0.0195 \text{ km}^2 \text{ yr}^{-1}$ .

### 3.3 Calving retreat of Imja-Lhotse Shar Glacier

The areal expansion of Imja Tsho is primarily in the eastward (up-glacier) direction due to the retreat of the calving front. The average calving retreat distances for 1992–2002, 2002–12, and 1992–2012 are shown in Table 3. The average calving retreat increased from  $316 \pm 201 \text{ m}$  during 1992 to 2002 to  $526 \pm 231 \text{ m}$  (max error = 30 m) from 2002 to 2012. The corresponding standard deviations of calving retreat of 201 m and 231 m, respectively during each decade, are large due to the calving front having an arm-like shape in 2002, which caused a non-uniform retreat of the calving front. These calving retreats correspond to calving rates of  $32 \pm 20 \text{ myr}^{-1}$  and  $53 \pm 23 \text{ myr}^{-1}$  (max error =  $3 \text{ myr}^{-1}$ ). The overall calving rate from 1992 to 2012 was  $43 \pm 8 \text{ myr}^{-1}$  (max error =  $3 \text{ myr}^{-1}$ ).

### 3.4 Drainable water from Imja Tsho

Using the bathymetric data reported above, we calculated the volume of water that could drain from Imja Tsho based on various levels of the lake surface. For example, the amount of water that could be drained from the lake is  $34.08 \pm 0.54 \text{ million m}^3$  if the lake surface elevation decreases 35 m from 5010 m to 4975 m (the elevation of the valley floor below the lake). The previous estimates of this volume were 15 million  $\text{m}^3$  (1992) and 21 million  $\text{m}^3$  (2002) (Sakai et al., 2003). The 2012 estimate is 40.5 % larger

than the 2002 value. If the lake were drained to a water surface elevation higher than the valley floor then the volume would decrease as shown in Fig. 7.

In the event of a breach of the former glacier terminus, water may not drain from the lake all at once and the timing or the hydrograph of the drainage is important in order to estimate the critical water volume that might cause serious damage downstream. However, detailed calculation of the volume and timing of discharge in the event of a breach of Imja Tsho requires extensive numerical simulations and is beyond the scope of this paper. Due to the continued areal expansion of the lake, there is an increasing amount of water that could drain from the lake in the event of a breach; however, this does not necessarily mean that the probability of occurrence of such an event increases.

### 3.5 GPR survey of Imja-Lhotse Shar Glacier

Figure 8 shows the results of the GPR survey for the transect across the Imja-Lhotse Shar glacier from north to south using a 10 Mhz antenna and assuming a velocity of propagation through the ice of  $167 \times 10^6 \text{ m s}^{-1}$ . The thickness of the glacier varies from  $40 \pm 9.27$  to  $60 \pm 9.27$  m thick near the lateral moraines to  $217 \pm 12.71$  m thick in the center of the glacier, significantly below the lake bottom. GPR surveys were also made in the western end of the lake in the moraine region, but the results are still being analyzed. The depth of mixed debris and ice in the western moraine end of the lake are difficult to determine from the GPR results.

## 4 Conclusions

The results of a 2012 bathymetric survey of Imja Tsho show that the lake has deepened from 98 m to  $116 \pm 0.25$  m between 2002 and 2012. Likewise, the volume has increased from  $35.8 \pm 0.7$  million  $\text{m}^3$  to  $61.6 \pm 1.8$  million  $\text{m}^3$  over the same period, a 70 % increase. The lake volume is increasing at a rate of  $2.58 \pm 0.25$  million  $\text{m}^3 \text{ yr}^{-1}$ , and the average

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**Table 1.** Comparison of Imja Tsho 2012 Bathymetric Survey Results with previous studies.

Study	No. of measurement points	Volume ( $10^6 \text{ m}^3$ )	Average Depth (m)	Maximum Depth (m)
1992 (Yamada and Sharma, 1993)	61	28.0	47.0	98.5
2002 (Sakai et al., 2003)	80	$35.8 \pm 0.7$	$41.6 \pm 0.5$	$90.5 \pm 0.5$
2012 (This study)	10 020	$61.6 \pm 1.8$	$48 \pm 2.5$	$116.3 \pm 0.25$

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**Table 2.** Imja Tsho Area Expansion 1992–2012.

Year	Icebergs (no.)	Melt Ponds (no.)	Lake Pixels (no.)	Perimeter Pixels (no.)	Area (km <sup>2</sup> )	Max. Error (km <sup>2</sup> )	Decade Expansion Rate (km <sup>2</sup> yr <sup>-1</sup> )	Max. Error (km <sup>2</sup> yr <sup>-1</sup> )
1992 <sup>1</sup>					0.60			
1992 <sup>3</sup>	0	12	720	162	0.648	0.073		
2002 <sup>2</sup>					0.868	0.037	0.026	
2002 <sup>3</sup>	0	28	963	202	0.867	0.091	0.022	0.0128
2012 <sup>3</sup>	15	2	1397	231	1.257	0.104	0.039	0.0195

<sup>1</sup> Yamada and Sharma (1993),

<sup>2</sup> Fujita et al. (2009, Table 1, p. 2),

<sup>3</sup> This study.

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**Table 3.** Calving retreat of Imja-Lhotse Shar Glacier for 1992–2012 based on landsat images.

Period	Calving Retreat			Calving Rate ( $\text{myr}^{-1}$ )
	Average (m)	Std. Dev. (m)	Max. Error (m)	
1992–2002	316	201	30	31.6
2002–2012	526	231	30	52.6
1992–2012	861	83	30	43.0

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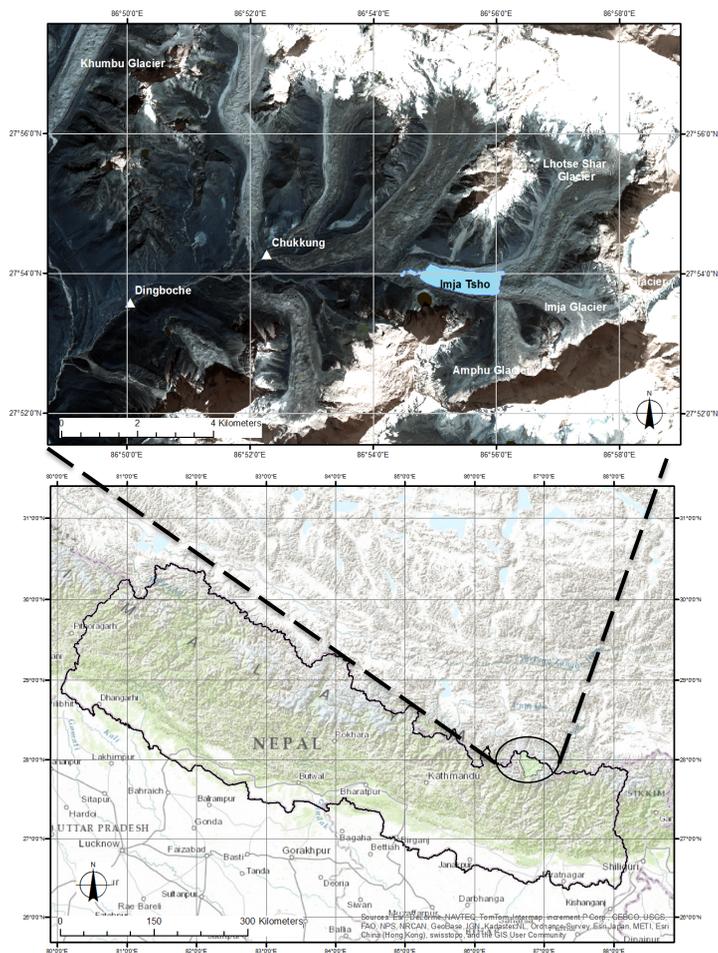
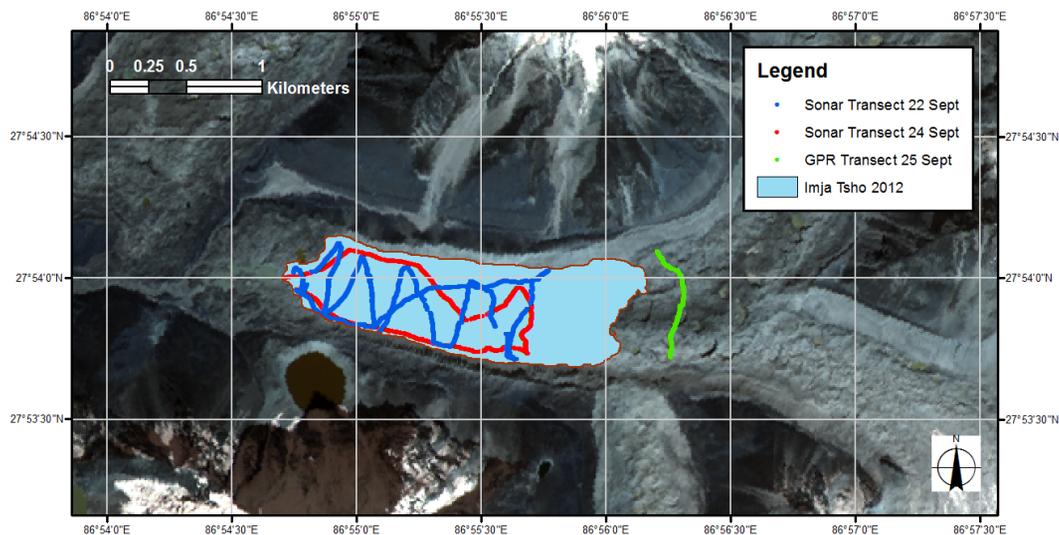


Fig. 1. Location of the Imja Tsho in the Khumbu region of Nepal.

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**Fig. 2.** Sonar bathymetric survey transects at Imja Tsho 22 September (red) and 24 (blue), and the GPR transect at Imja-Lhotse Shar glacier 25 September (green). The background is an ALOS image from 2008.

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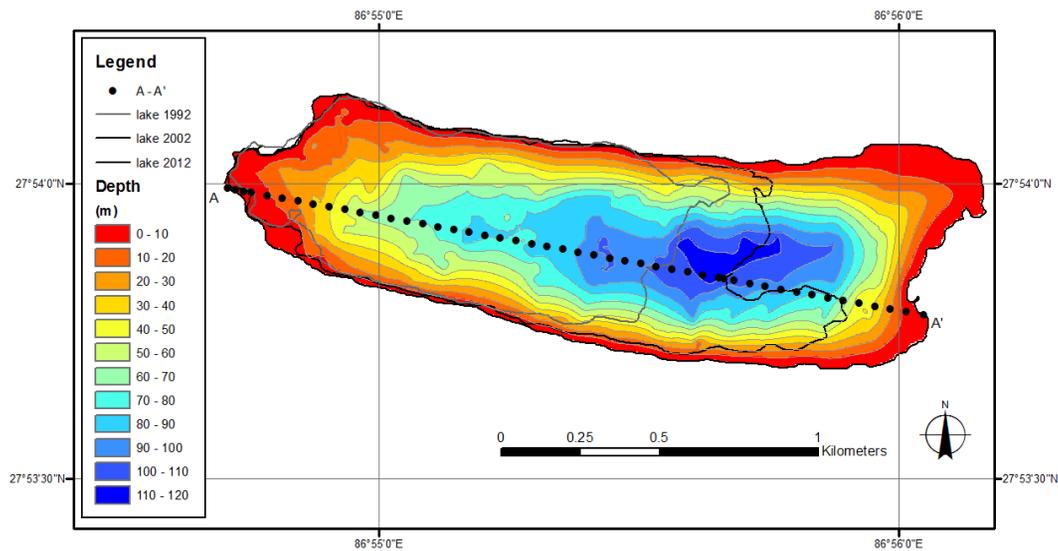
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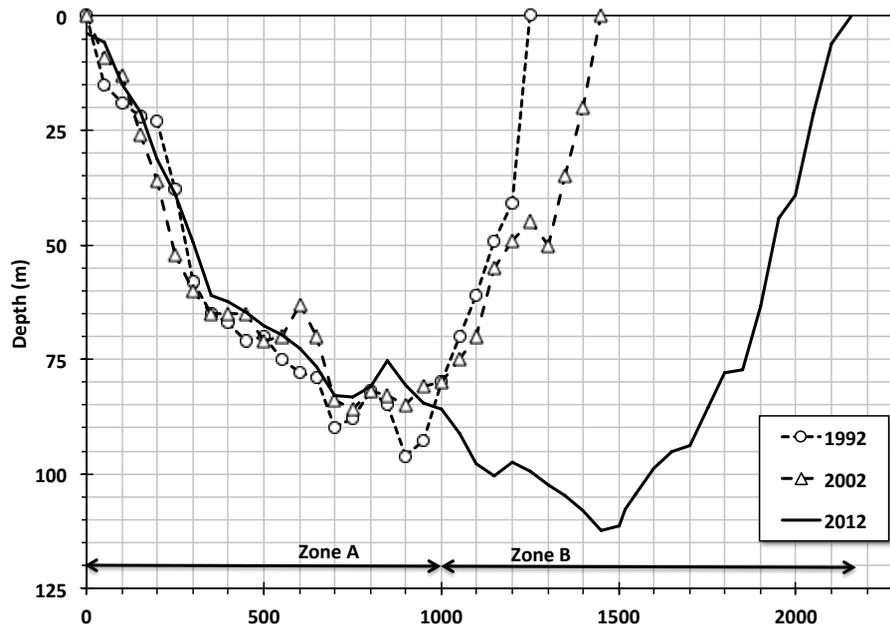
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**Fig. 3.** Bathymetric survey results from Imja Tsho in September 2012.

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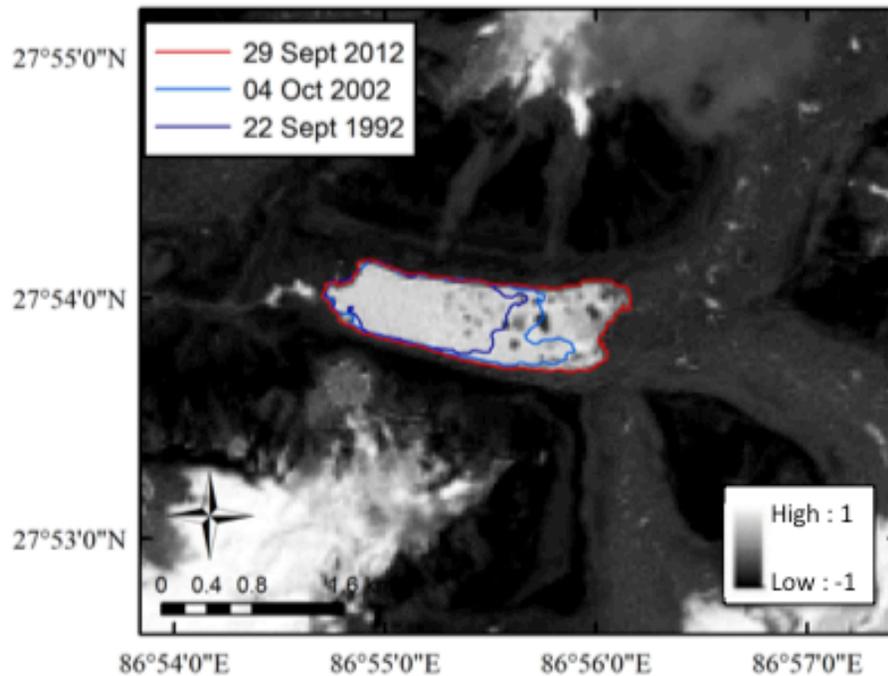


**Fig. 4.** Cross-section A-A' of 2012 bathymetric survey data for Imja Tsho compared to 1992 and 2002 surveys.

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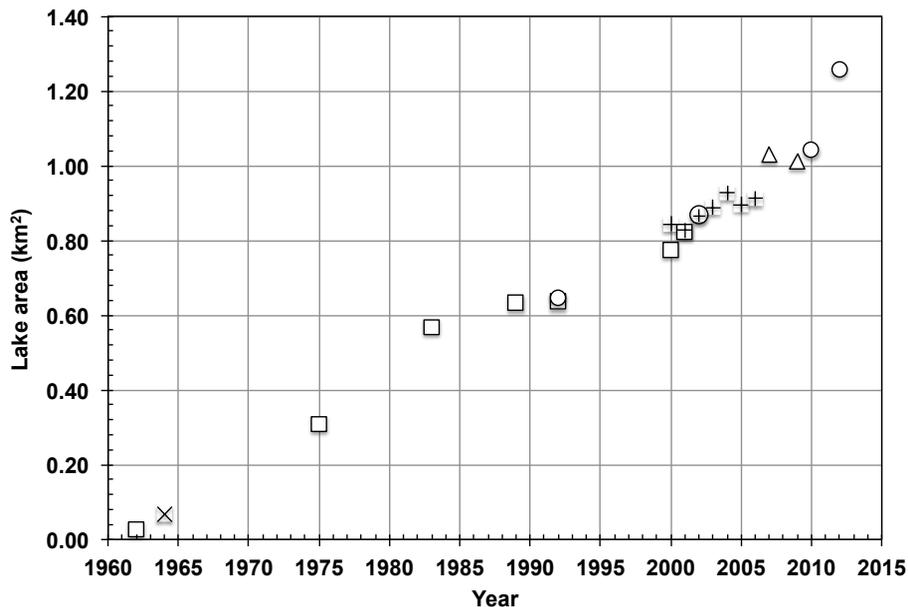


**Fig. 5.** NDWI calculated from Landsat images for 2012.

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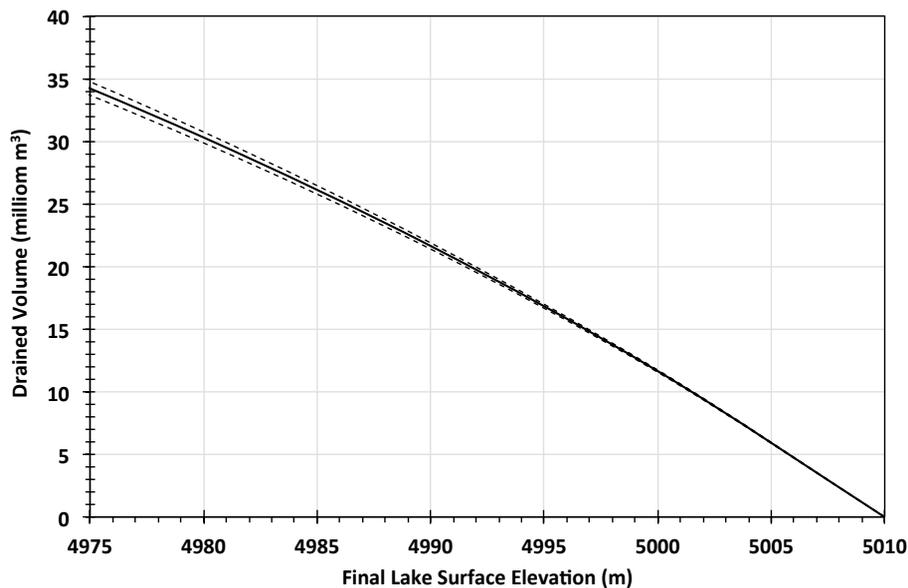


**Fig. 6.** Imja Tsho Area Expansion 1962–2012 (Source: □ – Bajracharya et al. (2007); ◇ – Yamada and Sharma (1993); + – Fujita et al. (2009); × – Lamsal et al. (2011); △ – Watanabe et al. (2009); and ○ – this study).

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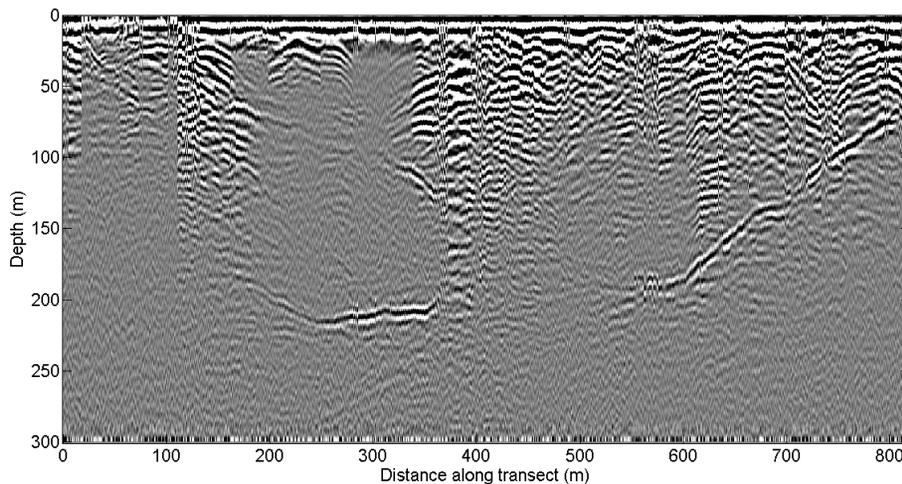
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**Fig. 7.** Potentially drained volume from Imja Tsho vs. lake surface elevation. Dashed lines show the calculated drained volume plus or minus one standard deviation.

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**Fig. 8.** GPR transect across Imja/Lhotse Shar glacier from north to south on 25 September 2012 using a 10 MHz antenna and velocity in ice of  $167 \times 10^6 \text{ ms}^{-1}$ .